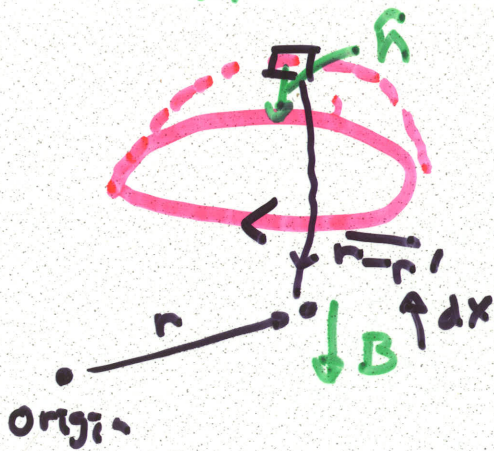


Solid Angle: 4π steradian = 100%

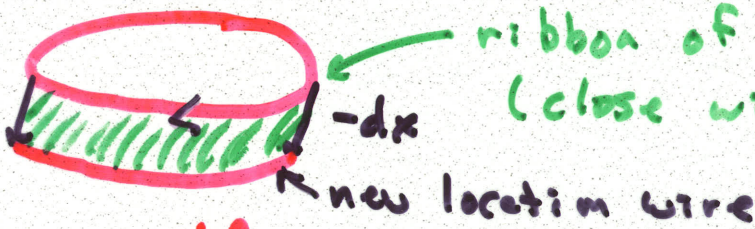
for sphere: $\Omega = \frac{\text{Area}}{R^2} = 2\pi(1 - \cos\theta)$
 (for area surrounding north pole)



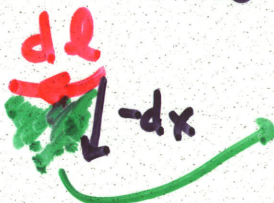
$$\Omega = \int \frac{\hat{n} \cdot (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3} dA$$

area adjusted by $\cos\theta$
 from dot product

Consider change in solid angle when observer moves distance $d\vec{x} \rightarrow$ circuit moves $-d\vec{x}$



ribbon of addition area
 (close with previous area)



$$-d\vec{x} \times d\vec{l}$$

$$-d\vec{x} \cdot d\vec{l} \times (\vec{r} - \vec{r}')$$

$$d\Omega = \int \frac{(-d\vec{x} \times d\vec{l}) \cdot (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

$$\partial\Omega \cdot d\vec{x}$$

so: $\frac{-\mu_0 I}{4\pi} \nabla\Omega = \vec{B}$

$$= -d\vec{x} \cdot \int \frac{d\vec{l} \times (\vec{r} - \vec{r}')}{|\vec{r} - \vec{r}'|^3}$$

Multipole expansion

$$\vec{A} = \frac{\mu_0 I}{4\pi} \oint \frac{d\vec{r}'}{|\vec{r} - \vec{r}'|} \approx_{r \rightarrow \infty} \frac{\mu_0}{4\pi} \frac{\vec{m} \times \vec{r}}{r^3}$$

$$\vec{B} \frac{4\pi}{\mu_0 I}$$

magnetic dipole

$$\vec{m} \equiv I \frac{1}{2} \oint \vec{r}' \times d\vec{r}' \rightarrow \text{Area}$$

Note: I've defined Ω with $\vec{r} - \vec{r}'$ vectors which is opposite of text book. I wanted $\vec{r}' - \vec{r}$

Forces & Torques

$$\oint \vec{E} = \vec{F}$$

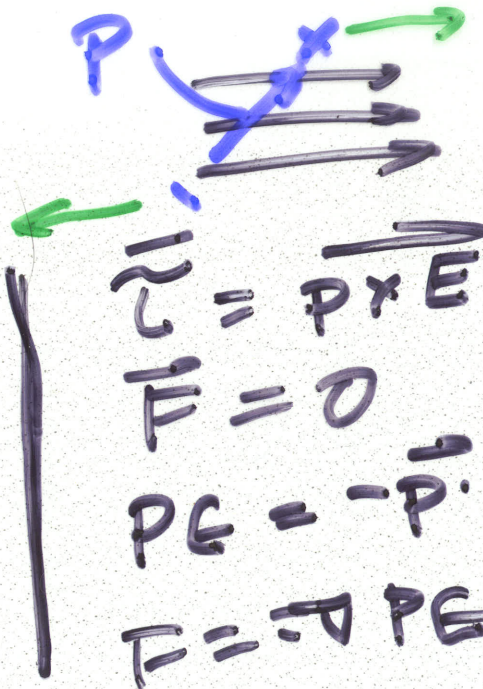
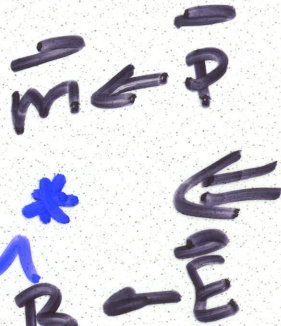
$$\oint \vec{v} \times \vec{B} = \vec{F}$$

① Trust?

② Love Tech*

③ Learn Why

Prove



$$\vec{A} \cdot \vec{B} = A_1 B_1 + \dots + A_n B_n = \sum A_i B_i$$

$$\vec{A} \times \vec{B} = (A_2 B_3 - A_3 B_2, \dots, \sum \epsilon_{ijk} A_j B_k)$$

↑
vector
Mechanics

$$R \vec{A} \times R \vec{B} = R(\vec{A} \times \vec{B})$$

$$\epsilon_{ijk} = \begin{cases} 0 & \text{if } i, j, k \text{ are not } 1, 2, 3 \\ +1 & \text{if } (i, j, k) \text{ is } (1, 2, 3) \\ -1 & \text{if } (i, j, k) \text{ is } (3, 2, 1) \end{cases}$$

$$\det(A) = \sum_{\sigma \in S_n} \text{sgn}(\sigma) A_{1\sigma_1} A_{2\sigma_2} \dots A_{n\sigma_n}$$

$$(\vec{A} \times \vec{B})_i = \sum_{j,k} \epsilon_{ijk} A_j B_k$$

$$\overline{(\vec{A} \times \vec{B})} = \sum_{i,j,k} \epsilon_{ijk} A_j B_k$$

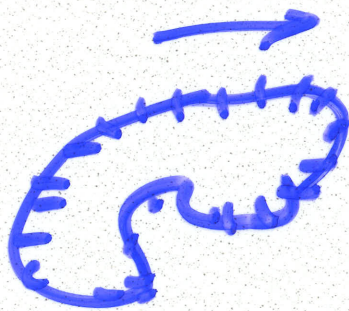
$$A \times (B \times C) = \overline{B} (A \cdot C) - \overline{C} (A \cdot B)$$

$\in G$

$$d\vec{\Gamma} = \int \delta \vec{\Gamma} \times \vec{B}$$

$$\vec{\Gamma} = \int \int \delta \vec{\Gamma} \times \vec{B}$$

$$= \int \int \delta \vec{\Gamma} \times \vec{B}$$



$$\vec{\Gamma} = \int \int \vec{F} \times (d\vec{r} \times \vec{B})$$

$$= \int \int d\vec{r} (\vec{F} \cdot \vec{B}) - \overline{\vec{B}} (\vec{F} \cdot d\vec{r})$$

1.2.1 p 22

$$\int \phi d\vec{l} = \int \nabla \phi \cdot d\vec{l}$$

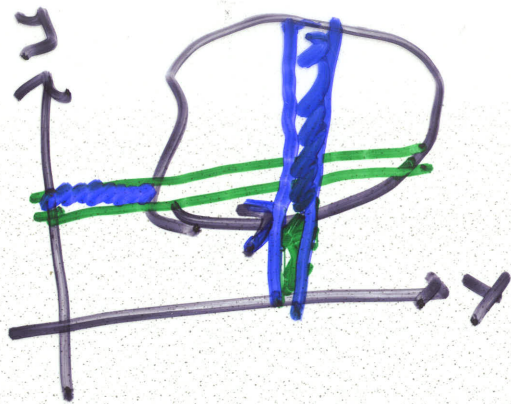
$$\int \nabla \phi \cdot d\vec{r} = \phi_f - \phi_i$$

$$\int \nabla \vec{A} \times \vec{B}$$

$$\times B_x + y B_y \hookrightarrow \vec{B}$$

$$\vec{\Gamma} = \int \int \underbrace{dr_i r_j B_j}_{\int dr_j} \int dy \times$$

$$\int dy \times$$



$$\int dy x = A$$

$$\int dx y = -A$$

$$0 = \oint d(r_i r_j) = \oint dr_i r_j + \int r_i dr_j$$

$$\uparrow \quad \uparrow \quad \uparrow$$

$$\tau_z = \mp \oint dr_i r_j B_j$$

$$\frac{1}{2} dr_i r_j - \frac{1}{2} r_i dr_j$$

$$= \frac{1}{2} \mp \int (\underset{\uparrow}{dr_i} r_j = r_i \underset{\uparrow}{dr_j}) B_j$$

$$\tau_z = \frac{1}{2} \mp \int \underset{\substack{\uparrow \\ \text{eye}}}{\vec{B}} \cdot \underset{\substack{\uparrow \\ \text{eye}}}{\vec{dr}} (r \cdot \vec{B}) - \vec{F} (dr \cdot \vec{B})$$

$\vec{B} \quad \vec{A} \cdot \vec{A} \quad \vec{B} \cdot \vec{A}$

$$= \frac{1}{2} \mp \int \vec{B} \cdot (dr \times r)$$

$$= \frac{1}{2} \mp \int \underbrace{(r \cdot dr)}_{\vec{M}} \cdot \vec{B}$$

$$\vec{A} = \frac{1}{2} \int \vec{r} \times d\vec{r}$$

$$A_x = \frac{1}{2} \int y dz - z dy$$

$\vec{F} = -\nabla PE$ $PE = -\vec{m} \cdot \vec{B}$
 $= \nabla (\vec{m} \cdot \vec{B}) = m_i \nabla B_i$

$$\partial_x (m_1 B_1 + \dots + m_2 B_2)$$

$$m_1 \partial_x B_1 + \dots + m_2 \partial_x B_2$$

$$\vec{F} = \mu \oint d\vec{l} \times \left(\vec{B}_0 + (\vec{r} \cdot \nabla) \vec{B} \right)$$

$$f(\vec{r}_0 + \Delta\vec{r}) = f(\vec{r}_0) + \Delta\vec{r} \cdot \nabla f$$

$$= \mu \oint d\vec{r} \times \left[(\vec{r} \cdot \nabla) \vec{B} \right]$$

$$F_i = \mu \oint \epsilon_{ijk} \underbrace{dr_j r_a \partial_a}_{\partial_a} B_k$$

$$= \epsilon_{ijk} \left[\epsilon_{jba} m_b \partial_a \right] B_k$$

$$(A \times B)_i = \epsilon_{ijk} A_j B_k$$

$$\square = m \times n$$

$$\vec{P} = (m \times n) \times B$$

$$= B \times (n \times m)$$

$$= n(m \cdot B) - m \underbrace{\vec{0} \cdot B}_{=0}$$

$$PE = -m \cdot B$$

$$\sum_{i=1}^3$$

$$\epsilon_{ijk} \epsilon_{iac} = \delta_{ja} \delta_{kb} - \delta_{jb} \delta_{ka}$$