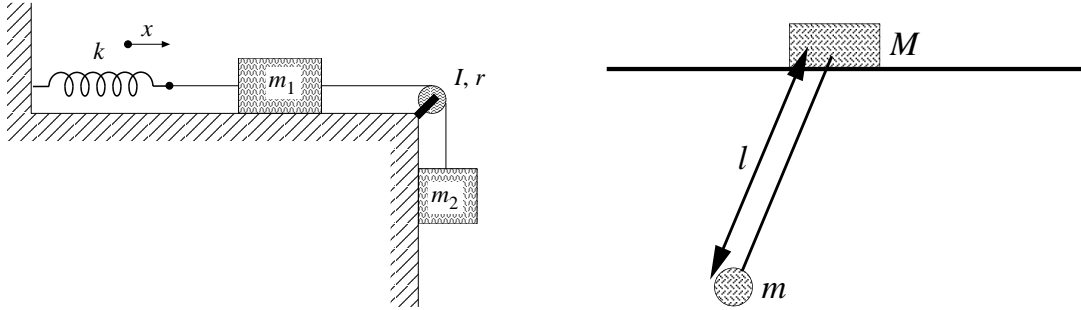
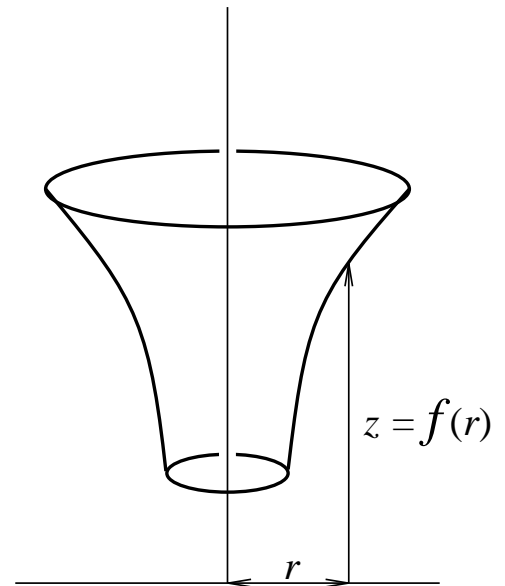


- Masses m_1 and m_2 are connected in the frictionless spring-and-pulley system shown below. The spring has spring constant k ; the pulley has radius r and moment of inertia I . The configuration of the system is described by x ; x is zero when the spring is relaxed. Find the Lagrangian for this system. Find the Hamiltonian for this system.



- Consider the motion of a frictionless glider (mass M) moving on a level air track with a pendulum (bob mass m , length l) attached to the glider.
 - Pick (and clearly define, perhaps with a picture) generalized coordinates for this problem.
 - Express the speed of the glider and the speed of the bob in terms of your coordinates.
 - Express the potential energy of the glider and the potential energy of the bob in terms of your coordinates.
 - Express the Lagrangian in terms of your coordinates.
 - Find the Hamiltonian for this system.
 - Write down the differential equations for your coordinates/momenta found from the Hamiltonian.

- Consider the problem of an object sliding frictionlessly down a cylindrically symmetric “drain” with height z a given function of the cylindrical radius r : $z = f(r)$. (The “drain” is a human sized object sitting in a convenience store on Earth.) Find the Lagrangian for this system. Find the Hamiltonian for this system. Is the Hamiltonian a constant of the motion? Is it equal to the energy? Notice that since θ (the polar angle in cylindrical coordinates) is cyclic there is a conserved quantity. Use this constant and the Hamiltonian to find an expression for time as an integral over r .



4. Consider the Lagrangian (m , q , and B are constants; $v_x = \dot{x}$, $v_y = \dot{y}$)

$$L_1 = \frac{1}{2}m(v_x^2 + v_y^2) + qBxv_y - V(x, y)$$

- (a) Find the differential equations (Euler-Lagrange equations) describing the motion of the particle.
- (b) Find the canonical momenta p_x and p_y
- (c) Find the Hamiltonian.
- (d) Find Hamilton's equations of motion from your Hamiltonian.
- (e) In lecture I discussed the Lagrangian:

$$L_2 = \frac{1}{2}m(v_x^2 + v_y^2) - qByv_x - V(x, y)$$

and got exactly the same equations of motion but most everything else was different. Show that $L_1 - L_2 = \frac{d}{dt}(\text{something})$. FYI: I claim that these two facts are related.